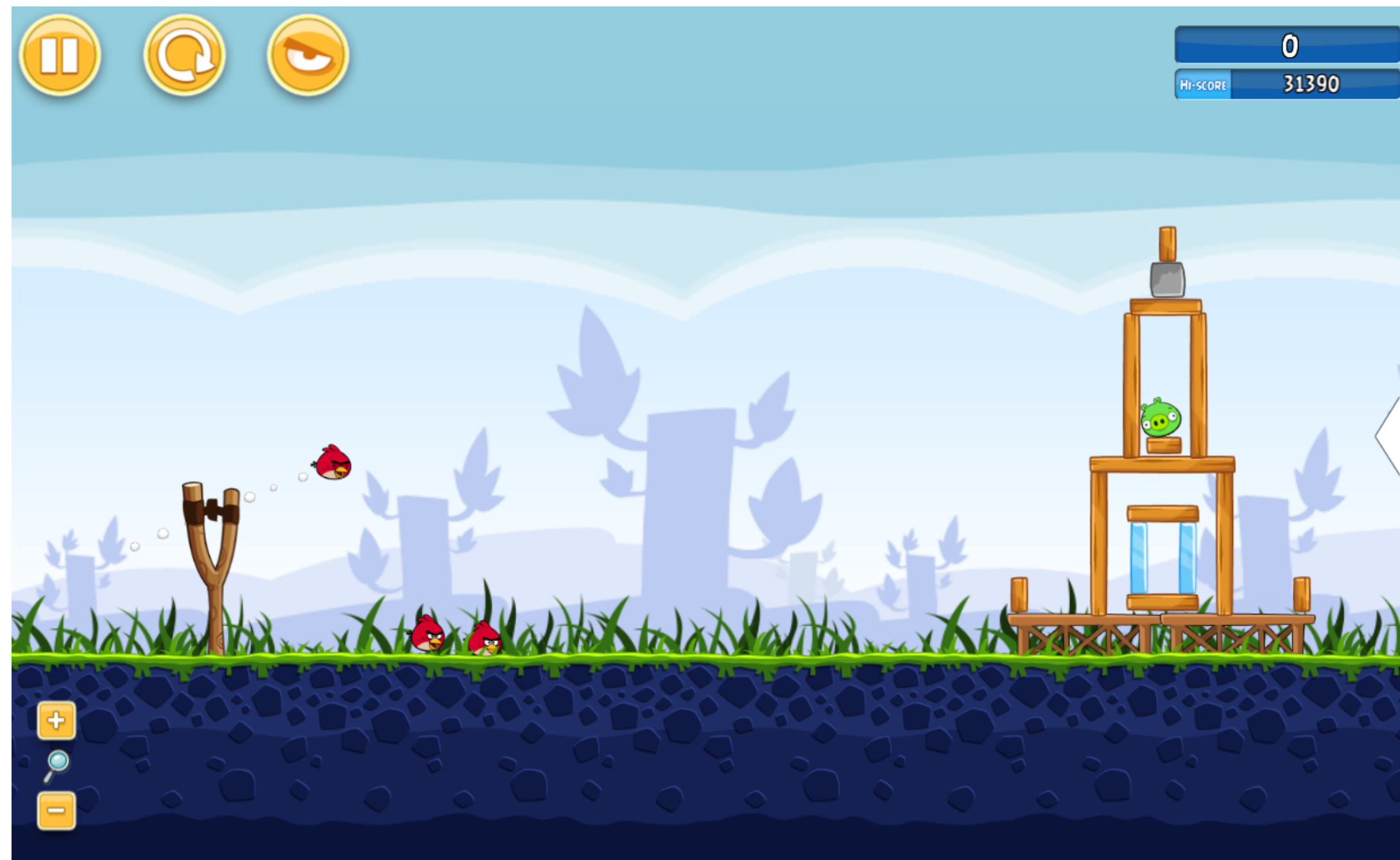


# AngryHEX: An Angry Birds-playing Agent based on HEX-Programs

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## 1. Motivation

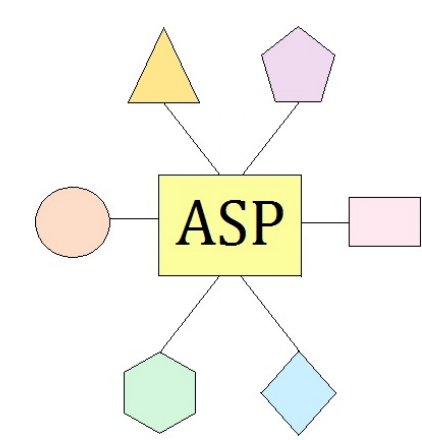
- ▶ **Angry Birds** (<http://www.angrybirds.com>) is a strategic arcade video game where the player uses a slingshot to shoot a limited number of **birds** at constructions aiming to destroy all **pigs** in the field



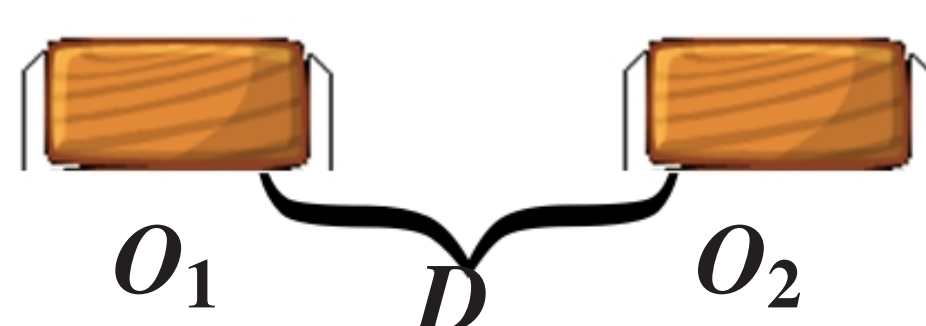
- ▶ **Goal:** Construct a **declarative agent** which plays the game
- ▶ **Challenge:** Plan **optimal shots** under consideration of physics
- ▶ **Our means:** **HEX-programs**, i.e., **Answer Set Programming (ASP)** with external sources and other extensions

## 2. HEX-Programs

- ▶ HEX-programs extend ASP by **external sources**
- ▶ Rule bodies may contain **external atoms**, e.g.



▶  $\&distance[O_1, O_2](D)$  is true iff distance between  $O_1$  and  $O_2$  is  $D$



▶  $\&canpush[ngobject](O_1, O_2)$  is true iff  $O_1$  can push  $O_2$  given additional info in extension of  $ngobject$

### Example

- ▶ Estimate likelihood that object  $O_2$  falls when object  $O_1$  is hit  
 $r1: \text{pushDamage}(O_2, P_1, P) \leftarrow \text{pushDamage}(O_1, -, P_1), P_1 > 0$



$\&canpush[ngobject](O_1, O_2),$   
 $\text{pushability}(O_2, P_2), P = P_1 * P_2 / 100.$

## 3. Architecture of our Agent

- ▶ We use the provided framework (**browser plugin**, **vision module** etc.)
- ▶ **Agent** builds on **tactic** and **strategy** both realized declaratively
- ▶ **Tactic:** reasoning about the next shot is done in a **HEX-program  $\Pi$** 
  - ▶ **Input:** scene info from the vision module (facts of  $\Pi$ )
  - ▶ **Output:** desired target (extracted from models of  $\Pi$ )
- ▶ **Strategy:** next level to played is computed in an ASP program  $\Pi'$ 
  - ▶ **Input:** info about the number of times levels were played, best scores achieved, scored of our agent, etc. encoded as facts
  - ▶ **Output:** next optimal level to be played

## 4. HEX-Encoding for Angry Birds Tactic

- ▶ **Physics simulation results** are accessed via **external atoms**, e.g.,
  - ▶ decide whether  $O_1$  falls whenever  $O_2$  falls
  - ▶ decide which  $O'$  intersect with trajectory of a bird after hitting  $O$
  - ▶ compute distances between  $O_1$  and  $O_2$
  - ▶ ...
- ▶ **Tactic in details:**
  - ▶ Consider each shootable **target** (objects which have a direct and unobstructed path from the slingshot)
  - ▶ Compute the **estimated damage** on each non-target object (discrete values), taking different bird types into account
  - ▶ **Rank the targets (=answer sets)** using **weak constraints**: add malus points for each pig, where the number of added malus points decreases with increasing likelihood that the pig is destroyed
  - ▶ **Learn from history:** never play a level in the same way more than once, look for new shots

## 5. ASP encoding for Angry Birds Strategy

- ▶ **Strategy in details:**
  - ▶ First play each level once
  - ▶ Then play levels in which our score maximally differs from the best
  - ▶ Play levels in which we played best and the difference to the second best score is minimal



## 5. Preliminary Benchmark Results

Level	ABC-AI	ABC-IS	HEX(2013)	HEX(2014)[n]
level 1	27550	30490	32090	31540 [7]
level 2	52420	34600	53460	44330 [10]
level 3	33460	41070	42370	41910 [6]
level 4	18690	27990	27970	<b>28520</b> [18]
level 5	36280	62780	63300	<b>69260</b> [13]
level 6	17870	17500	34810	34890 [9]
level 7	22510	20560	45710	45690 [11]
level 8	47400	40440	38730	<b>57070</b> [11]
level 9	35600	42500	43160	<b>51560</b> [12]
level 10	41530	43970	55660	55000 [9]
Sum	333310	361900	437260	<b>459770</b>

- ▶ ABC-AI: plain ASP
- ▶ ABC-IS: procedural implementation
- ▶ HEX(2013): HEX at IJCAI'13
- ▶ HEX(2014): HEX as by 17.08.14  
[n] : number of runs (strategy)

## 6. Results and Outlook

- ▶ **Results:**
  - ▶ Agent is realized using declarative programming means
  - ▶ New vision module provided by the organizers is integrated
  - ▶ Declarative strategy is realized (used to be in java)
  - ▶ Fixes and improvements
- ▶ **Possible improvements:**
  - ▶ **Combine objects** which behave like a single one
  - ▶ Plan over **multiple shots**



## 7. References

- ▶ Eiter, T., Ianni, G., Schindlauer, R., and Tompits, H. (2006). Effective Integration of Declarative Rules with External Evaluations for Semantic-Web Reasoning. ESWC'06 volume 4011, pages 273–287.

- ▶ Angry Birds AI competition Benchmark (<http://aibirds.org/benchmarks.html>)